

The extrinsic curvature of entire minimal graphs in $\mathbb{H}^2 \times \mathbb{R}$

J.M. Espinar*, M. Magdalena Rodríguez† and Harold Rosenberg‡

* Institut de Mathematiques, Université Paris VII, 175 Rue du Chevaleret, 75013 Paris, France; e-mail: jespinar@ugr.es

† Universidad Complutense de Madrid, Departamento de lgebra, Plaza de las Ciencias 3, 28040 Madrid , Spain; e-mail: magdalena@mat.ucm.es

‡ Instituto de Matematica Pura y Aplicada, 110 Estrada Dona Castorina, Rio de Janeiro 22460-320, Brazil; e-mail: rosen@impa.br

Abstract

We obtain an optimal estimate for the extrinsic curvature of an entire minimal graph in $\mathbb{H}^2 \times \mathbb{R}$, \mathbb{H}^2 the hyperbolic plane.

1 Introduction

Curvature estimates for minimal graphs in Euclidean space were first obtained by Heinz [3]. This work has been generalized by several authors [2, 4]. In this paper we will use an idea of R. Finn and R. Osserman [2], to obtain curvature estimates for entire minimal graphs in $\mathbb{H}^2 \times \mathbb{R}$.

The idea in [2] is to use the minimal graph of Scherk's surface over a square in the Euclidean plane to obtain an upper bound for the absolute value of the curvature of a minimal graph defined in a domain that contains the square.

*The author is partially supported by Spanish MEC-FEDER Grant MTM2007-65249, and Regional J. Andalucía Grants P06-FQM-01642 and FQM325

†Research partially supported by Spanish MEC/FEDER Grant MTM2007-61775 and Regional J. Andalucía Grant P06-FQM-01642.

This bound depends on the distance of the square to the boundary of the domain, and the geometry of the Scherk graph. When the squares enlarge to the entire Euclidean plane, the Scherk graphs converge to the constant solution. This gives yet another proof of Bernsteins' Theorem.

Given a “balanced” geodesic quadrilateral in the hyperbolic plane, there is a Scherk minimal graph defined in its interior. Moreover one can enlarge the quadrilateral so that the vertices are ideal points at infinity, and the Scherk graph still exists. This is what we use to obtain the optimal curvature estimates.

2 Scherk vertical minimal graphs in $\mathbb{H}^2 \times \mathbb{R}$

Let $\Omega \subset \mathbb{H}^2$ be an open domain. A function $u : \Omega \rightarrow \mathbb{R}$ defines a vertical minimal graph when

$$\operatorname{div} \left(\frac{\nabla u}{W} \right) = 0 \text{ in } \Omega, \quad (1)$$

where $W^2 = 1 + |\nabla u|^2$ (all terms calculated in the metric of \mathbb{H}^2).

Definition 2.1 *We say that D is a Scherk domain of \mathbb{H}^2 if it is bounded by four geodesics A_1, B_1, A_2, B_2 (consecutively ordered) so that they verify the following equilibrium condition: the sum of the lengths of A_1, A_2 coincides with the sum of the lengths of the edges B_1, B_2 . The geodesics are allowed to be ideal geodesics, with consecutive ideal geodesics asymptotic at their common ideal vertex of D (cf. Figure 1).*

In Theorem 3 of [5] and Theorem 1 of [1] it is proven that the equilibrium condition in the definition above allows one to construct a minimal graph on any Scherk domain, with boundary data $\pm\infty$ alternatively on consecutive boundary edges.

Definition 2.2 *We define a Scherk solution on a Scherk domain D of \mathbb{H}^2 as a minimal graph $u : D \rightarrow \mathbb{R}$ which takes the values $+\infty$ on $A_1 \cup A_2$ and $-\infty$ on $B_1 \cup B_2$.*

Now, we state the following results about the geometry of these Scherk graphs.

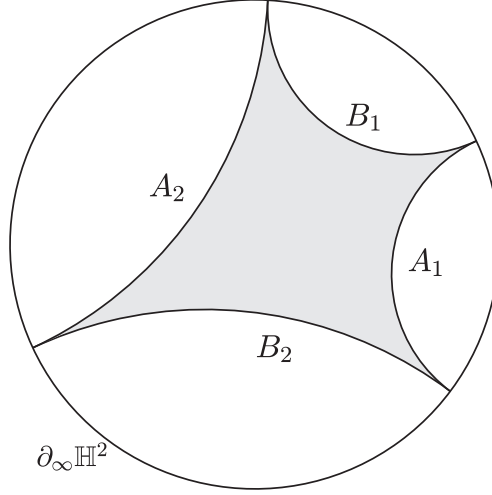


Figure 1: A Scherk domain $\mathbb{H}^2 \times \mathbb{R}$, bounded by ideal geodesics.

Lemma 2.3 *Let D be a Scherk domain of \mathbb{H}^2 and u be a Scherk solution on D . Then u has a unique critical point in D .*

Proof. The geometry of the graph of u near ∂D is explained in [5, 1]. For T large, there are two level curves of $u^{-1}(T)$ joining each of the vertices of A_1 and A_2 . Similarly for T near $-\infty$, $u^{-1}(T)$ contains two components joining the vertices of B_1 and B_2 (cf. Figure 2). Thus u has at least one critical point.

Let $p \in D$ and suppose p is a critical point of u . We will show that u has no other critical points.

By the maximum principle, we know that the level set $\Gamma = u^{-1}(u(p))$, in a neighborhood of p , consists of k smooth curves passing through p and meeting at equal angles at p (cf. Figure 3, left). Also $k \geq 2$. Thus there are at least four branches of Γ starting at p . Also, there are no compact cycles in Γ , again by the maximum principle.

Hence each branch of Γ starting at p , must diverge in D , perhaps passing through other critical points of u . Since Γ is proper in D and the values of u on the geodesics in ∂D are $\pm\infty$, each branch of Γ leaving p must converge to exactly one vertex of ∂D .

By the general maximum principle (the usual maximum principle, when D is bounded; or [1, Theorem 2], in the case D is an ideal polygon), no two

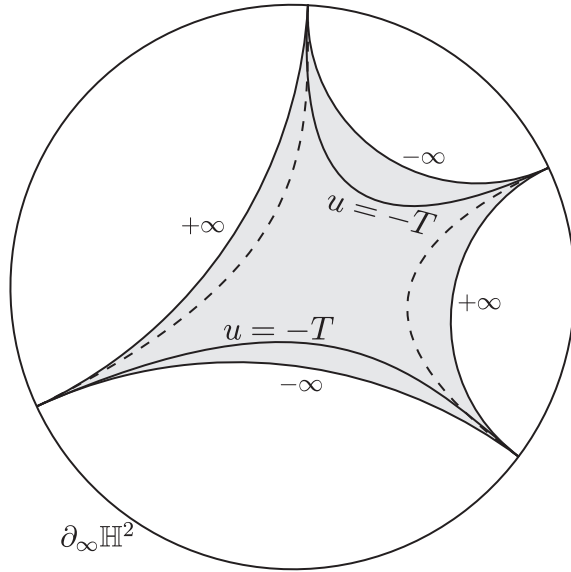


Figure 2: The level curves $u^{-1}(T)$ (the dotted lines) and level curves $u^{-1}(-T)$, for $T > 0$ large.

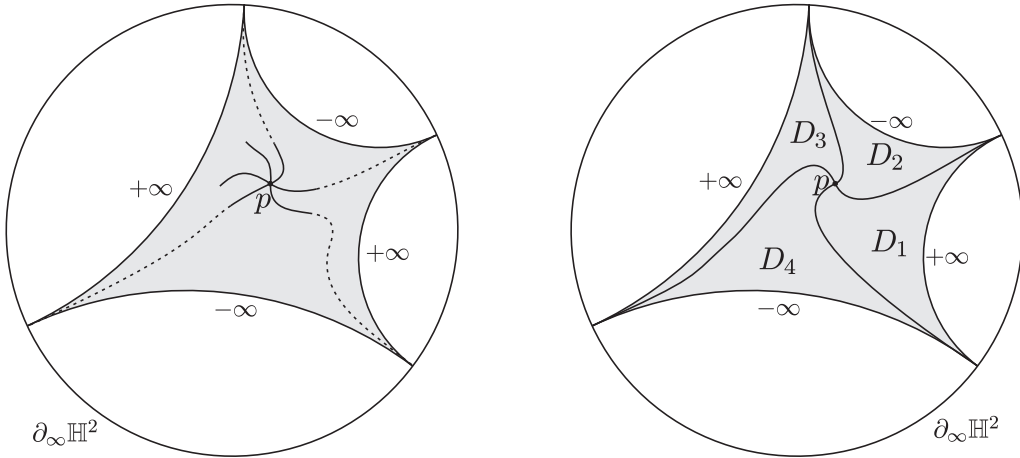


Figure 3: Left: Level set $\Gamma = u^{-1}(u(p))$, in a neighborhood of p , p is a critical point of u . Right: Disks defined by Γ .

branches leaving p can go to the same vertex of ∂D . Thus $k = 2$ and each

of the four branches of Γ leaving p go to a unique vertex of ∂D . This defines four topological disks in D : D_1, D_2, D_3, D_4 (cf. Figure 3, right).

Next observe that there can be no critical point of u on one of the branches of Γ leaving p (other than p). For suppose q were such a critical point of u , q on a branch α of Γ , α separates D_1 and D_2 say. Again by the maximum principle, there is another branch β of Γ passing through q , β transverse to α at q . Consider the branch β_1 of β leaving q and entering D_1 . This branch can not leave D_1 at a point of $\partial D_1 \cap D$ since this would give a compact cycle in Γ . Thus β_1 goes to one of the two vertices of $\partial D_1 \cap \partial D$. This is impossible by the general maximum principle.

Now we see that u can have no critical points other than p . For if q were such a point, it would be in the interior of D_1 say, and there would be four branches of $u^{-1}(u(q))$, leaving q , and going to the four vertices of ∂D . These four branches have no other critical points of u .

By separation properties, these four branches intersect the four branches of Γ starting at p , which contradicts the maximum principle. \square

Lemma 2.4 *Let D be a Scherk domain of \mathbb{H}^2 and u a Scherk solution on D . Let p be the unique point where $|\nabla u(p)| = 0$. Then the extrinsic curvature K_{ext} of u does not vanish at p .*

Proof. Consider the half-space model of the hyperbolic plane, $\mathbb{H}^2 = \{(x, y) \in \mathbb{R}^2 \mid y > 0\}$. Up to a translation, we can assume $p = (0, 1)$.

The formula for the extrinsic curvature we derive in Section 4 is

$$K_{ext} = \frac{y^2}{W^4} ((yu_{xx} - u_y)(yu_{yy} + u_x) - (yu_{xy} + u_x)^2).$$

At p , $u_x = 0 = u_y$, $y = 1$ and $W = 1$. Hence

$$K_{ext} = u_{xx}u_{yy} - u_{xy}^2.$$

Thus if $K_{ext}(p) = 0$, then

$$u_{xx}u_{yy} = u_{xy}^2 \text{ at } p. \quad (2)$$

In Section 4, the minimal surface equation for u is written:

$$(1 + y^2 u_x^2)u_{yy} + (1 + y^2 u_y^2)u_{xx} - 2y^2 u_x u_y u_{xy} - y u_y (u_x^2 + u_y^2) = 0. \quad (3)$$

Hence at p , we have

$$u_{yy} + u_{xx} = 0.$$

Combining this with the above equation (2), we conclude

$$u_{xx} = u_{yy} = u_{xy} = 0 \text{ at } p.$$

We conclude that the solution $v \equiv 0$ and u have 2'nd order contact at p . By the Maximum Principle, $u = 0$, near p , consists of k curves meeting at equals angles at p , and $k \geq 3$. Thus, there are at least 6 branches of $u = 0$ leaving p . Again, by the Maximum Principle, none of the curves in $u = 0$ can be compact cycles. Thus there are at least 2 of the branches of $u = 0$ (starting at p) that go to the same vertex of ∂D (there are only 4 vertices). This is impossible by the General Maximum Principle [1, Theorem 2]. This proves $K_{ext}(p) \neq 0$. \square

Lemma 2.5 *Let u be a Scherk solution on a Scherk domain $D \subset \mathbb{H}^2$. Then the extrinsic curvature of u never vanishes.*

Proof. Consider the half-space model of \mathbb{H}^2 and let $\gamma \subset \mathbb{H}^2 \times \{0\}$ be the complete geodesic with $x = 0$. The end points of γ divide the boundary $\partial_\infty \mathbb{H}^2$ at infinity (at height zero) into two parts, say C^+ and C^- . Let $\Gamma \subset \partial_\infty \mathbb{H}^2 \times \mathbb{R}$ be the curve given by the union of $C^+ \times \{t\}$, $C^- \times \{-t\}$ and the vertical segments joining the end points of $C^+ \times \{t\}$ and $C^- \times \{-t\}$. There exists an entire minimal graph v_t invariant under translations along γ (in particular, $(v_t)_y(0, 1) = 0$), which takes values t when it approaches to $C^+ \times \{t\}$ and $-t$ when it approaches to $C^- \times \{-t\}$ (see [6, Appendix A]).

It is not hard to see that γ is contained in the graph and the extrinsic curvature of the graph along γ vanishes. This fact follows since the profile curve has an inflection point when passes through γ . Moreover, the tangent plane along γ is becoming horizontal as t goes to zero, and vertical as t goes to $+\infty$.

Let D be the Scherk domain, and $q \in D$ a point with $K_{ext}(q) = 0$. Up to a translation and a rotation about a vertical axis, we can assume $q = (0, 1)$ and $u_y(q) = 0$.

Now choose t so that $(v_t)_x(q) = u_x(q)$ (i.e. u, v_t have the same tangent plane at q). In particular, u and $v = v_t$ have contact of order at least one.

Since both u, v have vanishing extrinsic curvature at q , Lemma 4.1 says that, at q ,

$$\begin{aligned}(1 + u_x^2)u_{yy} &= -u_{xx} \\ (1 + v_x^2)v_{yy} &= -v_{xx} \\ (1 + u_x^2)u_{yy}^2 &= -(u_{xy} + u_x)^2 \\ (1 + v_x^2)v_{yy}^2 &= -(v_{xy} + v_x)^2\end{aligned}$$

Hence $u_{yy}(q) = 0 = v_{yy}(q)$, and so $u_{xx}(q) = 0 = v_{xx}(q)$. Also

$$u_{xy}(q) + u_x(q) = 0 = v_{xy}(q) + v_x(q),$$

from where we deduce $u_{xy}(q) = v_{xy}(q)$, since $u_x(q) = v_x(q)$.

Thus, u and v have contact of order at least two at q . We finish as in the proof of Lemma 2.4. \square

Lemma 2.6 *Let D be a Scherk domain of \mathbb{H}^2 and u a Scherk solution on D . Orient the graph Σ of u by the upward pointing unit normal N and define $\nu = \langle N, \partial_t \rangle$ on D . Then ν has exactly one critical point: the point p where $N = \partial_t$.*

Proof. By Lemma 2.3, there is only one point $p \in D$ with $\nu(p) = 1$. Thus from Lemma 2.5 it suffices to prove that, if $q \in D$ is a critical point of ν with $0 < \nu(q) < 1$, then $K_{ext}(q) = 0$.

We have, for any $X \in T_{(q, u(q))}\Sigma$,

$$d\nu_q(X) = \langle \nabla_X N, \xi \rangle = -\langle S_q X, \xi \rangle,$$

where ∇ is the Riemannian connection in $\mathbb{H}^2 \times \mathbb{R}$ and S_q is the shape operator of Σ .

Were q a critical point of ν , we would have $\langle S_q X, \xi \rangle = 0$ for all $X \in T_{(q, u(q))}\Sigma$. If $0 < \nu(q) < 1$, the tangent plane at q is not horizontal, and S_q would have rank zero. And then $K_{ext}(q) = 0$. \square

3 A family of symmetric Scherk graphs in $\mathbb{H}^2 \times \mathbb{R}$

In this section we consider the Poincaré disk model of \mathbb{H}^2 ,

$$\mathbb{D} = \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1^2 + x_2^2 < 1\}$$

with the hyperbolic metric $g_{-1} = \frac{4}{(1-x_1^2-x_2^2)^2}g_0$, where g_0 is the canonical metric in \mathbb{R}^2 . We take in $\mathbb{H}^2 \times \mathbb{R}$ the usual product metric

$$ds^2 = \frac{4}{(1-x_1^2-x_2^2)^2}(dx_1^2 + dx_2^2) + dt^2.$$

For each $\lambda \in (0, +\infty]$, consider the geodesic square D_λ whose vertices are the points in the geodesics $\{x_1 = \pm x_2\}$ at distance λ from the origin (c.f. Figure 4). Note that for $\lambda = +\infty$, D_λ is an ideal polygon (its vertices are at the boundary at infinity $\partial_\infty \mathbb{H}^2$ of \mathbb{H}^2). We know [5, 1, 6] there exists a unique minimal (vertical) graph

$$u_\lambda : D_\lambda \rightarrow \mathbb{R}$$

in $\mathbb{H}^2 \times \mathbb{R}$ which takes boundary values $+\infty$ on two opposite edges, say

$$A_1 = \partial D_\lambda \cap \{x_1 > |x_2|\} \quad \text{and} \quad A_2 = \partial D_\lambda \cap \{x_1 < -|x_2|\};$$

goes to $-\infty$ on the other two boundary arcs

$$B_1 = \partial D_\lambda \cap \{x_2 > |x_1|\} \quad \text{and} \quad B_2 = \partial D_\lambda \cap \{x_2 < -|x_1|\};$$

and vanishes on

$$\Gamma_1 = D_\lambda \cap \{x_1 = x_2\} \quad \text{and} \quad \Gamma_2 = D_\lambda \cap \{x_1 = -x_2\}.$$

By uniqueness, the graph of u_λ is symmetric with respect to the totally geodesic vertical planes $\{x_i = 0\}$, $i = 1, 2$.

Henceforth in this section, set $D = D_\lambda$ and $u = u_\lambda$. Let $\{V_1, V_2\}$ be an orthonormal frame on the graph $\Sigma = \Sigma_\lambda$ of u , tangent to the principal directions and positively oriented. This frame is well defined on Σ by Lemmas 2.3 and 2.6.

For every $q \in \Sigma$, q not equal to the origin, denote by

$$\pi_q : T_q(\mathbb{H}^2 \times \mathbb{R}) \rightarrow T_q \Sigma$$

the orthogonal projection onto the tangent plane $T_q \Sigma$, and by $N(q)$ the upward pointing unit normal vector to Σ at q . Also call

$$\theta(q) = \angle(V_2(q), \pi_q(\partial_t))$$

the oriented angle in $T_q \Sigma$ from $V_2(q)$ to $\pi_q(\partial_t)$.

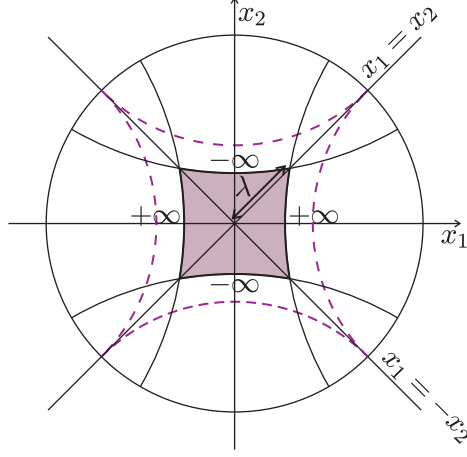


Figure 4: Scherk domain D_λ .

Lemma 3.1 *For every $\nu_0 \in (0, 1)$ and every $\theta_0 \in [0, 2\pi)$, there exists a point $q \in \Sigma$ such that $\nu(q) := \langle N(q), \partial_t \rangle = \nu_0$ and $\theta(q) = \theta_0$.*

Proof. For every $\nu_0 \in (0, 1]$, consider

$$\mathcal{C}_{\nu_0} = \{q \in \Sigma \mid \nu(q) = \langle N(q), \partial_t \rangle = \nu_0\}.$$

By Lemma 2.6, the sets \mathcal{C}_{ν_0} , $\nu_0 \in (0, 1)$, foliate $\Sigma - \{(0, 0, 0)\}$. So it suffices to show the total variation of the function θ is 2π on each \mathcal{C}_{ν_0} .

Let $\Pi_i = \{x_i = 0\} \subset \mathbb{H}^2 \times \mathbb{R}$, $i = 1, 2$. Each Π_i is a totally geodesic vertical plane in $\mathbb{H}^2 \times \mathbb{R}$, which is a plane of symmetry of Σ . Hence the curve $\tilde{\alpha}_i$ of intersection of this plane with Σ is a line of curvature of Σ , and the normal to Σ is in the plane Π_i along $\tilde{\alpha}_i$, $i = 1, 2$.

By vertical projection to D , we can think of θ as defined on $D - \{(0, 0)\}$. Along the positive x_1 -axis, the vector $\pi_{q_1}(\partial_t)$ points to the positive x_1 -axis, for every $q_1 \in \tilde{\alpha}_1$, hence $\theta(q_1) = -\pi/2$. Along the geodesic $\{x_1 = x_2 > 0\}$, the normal to Σ is orthogonal to this geodesic, hence $|\theta| = \pi/4$. For q_2 on the x_2 -axis, the vector $\pi_{q_2}(\partial_t)$ points to the x_2 -axis, and $\theta(q_2) = 0$.

At the origin, $V_1 = \partial_{x_1}$ and $V_2 = \partial_{x_2}$. Hence for $\nu < 1$, ν near 1, the total variation of θ on the arc of \mathcal{C}_ν in the first quadrant $\{x_1 > 0, x_2 > 0\}$ is $\pi/2$. The variation of θ in the other three quadrants is obtained by symmetry. Hence on \mathcal{C}_ν , the variation of θ is 2π .

Since θ is continuous, the variation of θ is 2π on each \mathcal{C}_ν , $0 < \nu < 1$. \square

4 Extrinsic curvature and principal directions of vertical minimal graphs in $\mathbb{H}^2 \times \mathbb{R}$

From now on (unless otherwise stated), we consider the half-plane model of \mathbb{H}^2 ,

$$\mathbb{H}^2 = \{(x, y) \in \mathbb{R}^2 \mid y > 0\}.$$

Denote by $p = (x, y)$ the coordinates in \mathbb{H}^2 and by t the coordinate in \mathbb{R} . Then the metric in $\mathbb{H}^2 \times \mathbb{R}$ is given by $d\sigma^2 = \frac{1}{y^2}(dx^2 + dy^2) + dt^2$.

Consider $u : \Omega \subset \mathbb{H}^2 \rightarrow \mathbb{R}$, and denote by Σ the graph of u . Then Σ can be parameterized by

$$F(x, y) = (x, y, u(x, y)),$$

for $(x, y) \in \mathbb{H}^2$. A basis of the tangent bundle of Σ is given by

$$F_x = (1, 0, u_x) \quad \text{and} \quad F_y = (0, 1, u_y)$$

and the upward pointing unit normal N is given by

$$N = \frac{1}{W}(-y^2 u_x, -y^2 u_y, 1)$$

where $W^2 = 1 + y^2(u_x^2 + u_y^2)$.

Denote by ∇ the Riemannian connection in $\mathbb{H}^2 \times \mathbb{R}$. The coefficients of the second fundamental form of Σ are given by (see [7])

$$\begin{aligned} \langle \nabla_{F_x} F_x, N \rangle &= \frac{1}{yW}(yu_{xx} - u_y) \\ \langle \nabla_{F_x} F_y, N \rangle &= \frac{1}{yW}(yu_{xy} + u_x) \\ \langle \nabla_{F_y} F_y, N \rangle &= \frac{1}{yW}(yu_{yy} + u_y) \end{aligned}$$

From this, we can deduce that the extrinsic curvature of Σ at the point $(x, y, u(x, y))$ is given by

$$K_{ext} = \frac{y^2}{W^4} ((yu_{xx} - u_y)(yu_{yy} + u_y) - (yu_{xy} + u_x)^2),$$

and Σ is a minimal surface if

$$(1 + y^2 u_x^2)u_{yy} + (1 + y^2 u_y^2)u_{xx} - 2y^2 u_x u_y u_{xy} - y u_y (u_x^2 + u_y^2) = 0. \quad (4)$$

Let p be a point in \mathbb{H}^2 . After a translation, we can assume $p = (0, 1)$.

Also, we can rotate Σ about the t -axis corresponding to the \mathbb{R} factor so that $u_y(p) = 0$.

Consider the orthonormal basis $\{X_p = \frac{F_x(p)}{|F_x(p)|}, Y_p = \frac{F_y(p)}{|F_y(p)|}\}$ of the tangent plane $T_{\bar{p}}\Sigma$, with $\bar{p} = (p, u(p))$,

$$X_p = \frac{1}{W(p)}(1, 0, u_x(p)) \quad \text{and} \quad Y_p = (0, 1, 0).$$

In what follows, we will work at p , so we will sometimes omit the dependence on p .

Lemma 4.1 *Let u be a minimal vertical graph in $\mathbb{H}^2 \times \mathbb{R}$. Suppose u is defined at $p = (0, 1)$ and $u_y(p) = 0$. Then $u_{xx}(p) = -W(p)^2 u_{yy}(p)$, and the extrinsic curvature of Σ at $\bar{p} = (p, u(p))$ is given by*

$$K_{ext}(p) = \frac{-1}{W(p)^4} (W(p)^2 u_{yy}(p)^2 + T_u(p)^2),$$

where $T_u = u_{xy} + u_x$. Furthermore, if $E = aX + bY$ is a principal direction of Σ at $\bar{p} = (p, u(p))$, associated to the principal curvature $k_1 = \sqrt{-K_{ext}}$, then we have

$$\begin{cases} bT_u(p) = (W(p)^2 k_1(p) + W(p)u_{yy}(p))a \\ aT_u(p) = (W(p)^2 k_1(p) - W(p)u_{yy}(p))b \end{cases}$$

Proof. From the minimal graph equation (4) we obtain that

$$u_{xx}(p) = -W(p)^2 u_{yy}(p). \quad (5)$$

With respect to the basis $\{X, Y\}$, the coefficients of the second fundamental form of Σ at p are given by

$$\begin{aligned} \langle \nabla_X X, N \rangle &= \frac{1}{|F_x|^2} \langle \nabla_{F_x} F_x, N \rangle = \frac{1}{W^3} u_{xx} \stackrel{(5)}{=} \frac{-1}{W} u_{yy} \\ \langle \nabla_X Y, N \rangle &= \frac{1}{|F_x|} \langle \nabla_{F_x} F_y, N \rangle = \frac{1}{W^2} T_u \\ \langle \nabla_Y Y, N \rangle &= \langle \nabla_{F_y} F_y, N \rangle = \frac{1}{W} u_{yy} \end{aligned}$$

The lemma follows easily from here and the next equality

$$\begin{pmatrix} -\frac{u_{yy}}{W} & \frac{T_u}{W^2} \\ \frac{T_u}{W^2} & \frac{u_{yy}}{W} \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = k_1 \begin{pmatrix} a \\ b \end{pmatrix}$$

□

5 A bound for the extrinsic curvature

Let $u : \mathbb{H}^2 \rightarrow \mathbb{R}$ be an entire vertical minimal graph, and $p \in \mathbb{H}^2$. After a translation and a rotation around the t -axis, we can assume $p = (0, 1)$, $u(p) = 0$ and $u_y(p) = 0$.

For each $\lambda \in (0, +\infty]$, consider D_λ, u_λ as in Section 3. Observe that we can translate and rotate the graph Σ_λ of u_λ so that Σ and Σ_λ are tangent at \bar{p} and have the same principal directions at \bar{p} .

For if p is a critical point of u , then it is also the unique critical point of u_λ so a rotation about the vertical geodesic through \bar{p} will make the principal directions coincide.

When p is not a critical point of u , then by Lemma 3.1, there exists a point $q \in D_\lambda$, such that $\nu_\lambda(q) = \nu(p)$ and $\theta_\lambda(q) = \theta(p)$ (by vertical projection, we can think of the angle functions $\nu_\lambda, \theta_\lambda$ defined on D_λ , and ν, θ defined on \mathbb{H}^2).

We can translate the Scherk surface Σ_λ horizontally to have $q = p = (0, 1)$ (now D_λ is no longer “centered” at the origin) and vertically to get $u_\lambda(p) = u(p) = 0$. And we rotate Σ_λ about the t -axis to obtain $N_\lambda(p) = N(p)$, where N_λ, N are the normal vectors to Σ_λ, Σ , respectively.

Hence Σ_λ and Σ are minimal surfaces tangent at \bar{p} , with the same principal directions at \bar{p} .

Proposition 5.1 *Assume Σ and Σ_λ are tangent at \bar{p} with the same principal directions. Then the absolute extrinsic curvature $|K_{ext}|$ of Σ at p is strictly smaller than the absolute extrinsic curvature of Σ_λ at p , for every $\lambda \in (0, +\infty]$.*

Proof. As we have seen above, we can get after a translation and a rotation about the t -axis, that Σ_λ, Σ are tangent at \bar{p} , so

$$(u_\lambda)_x(p) = u_x(p), \quad (u_\lambda)_y(p) = u_y(p) = 0;$$

and they have the same principal directions at \bar{p} , that is

$$a_\lambda = a, \quad b_\lambda = b,$$

where a, b are defined in Lemma 4.1.

In particular, $W(p)^2 = 1 + u_x(p)^2 = 1 + (u_\lambda)_x(p)^2$. From Lemma 4.1 we obtain

$$\begin{cases} bT_u = (W^2k_1 + Wu_{yy})a \\ bT_{u_\lambda} = (W^2k_1^\lambda + W(u_\lambda)_{yy})a \\ aT_u = (W^2k_1 - Wu_{yy})b \\ aT_{u_\lambda} = (W^2k_1^\lambda - W(u_\lambda)_{yy})b \end{cases} \quad (6)$$

at p , where k_1, k_1^λ are, respectively, the positive principal curvature of Σ, Σ_λ .

Claim 5.2 *If there exists $\lambda \in (0, +\infty]$ such that the extrinsic curvature of Σ_λ at p coincides with the extrinsic curvature K_{ext} of Σ at p , then*

$$T_u(p) = T_{u_\lambda}(p) \quad \text{and} \quad u_{yy}(p) = (u_\lambda)_{yy}(p).$$

Suppose the extrinsic curvature of Σ_λ at p coincides with the extrinsic curvature of Σ at p . Then $k_1^\lambda(p) = k_1(p)$. From (6) we get

$$\begin{cases} b(T_u(p) - T_{u_\lambda}(p)) = Wa(u_{yy}(p) - (u_\lambda)_{yy}(p)) \\ a(T_u(p) - T_{u_\lambda}(p)) = Wb((u_\lambda)_{yy}(p) - u_{yy}(p)) \end{cases} \quad (7)$$

If $a = 0$ or $b = 0$, then $T_u(p) = T_{u_\lambda}(p)$ and $u_{yy}(p) = (u_\lambda)_{yy}(p)$, as we wanted to prove. Otherwise,

$$\frac{a}{b}(u_{yy}(p) - (u_\lambda)_{yy}(p)) = \frac{b}{a}((u_\lambda)_{yy}(p) - u_{yy}(p))$$

and then

$$\left(\frac{a}{b} + \frac{b}{a}\right)u_{yy}(p) = \left(\frac{a}{b} + \frac{b}{a}\right)(u_\lambda)_{yy}(p)$$

Hence $u_{yy}(p) = (u_\lambda)_{yy}(p)$. We also get $T_u(p) = T_{u_\lambda}(p)$ from (7), and Claim 5.2 follows.

We deduce from Claim 5.2 and from the minimal equation (5) that u, u_λ have contact of order at least two at p ; that is

- $u(p) = u_\lambda(p)$,
- $u_x(p) = (u_\lambda)_x(p), \quad u_y(p) = (u_\lambda)_y(p)$,
- $u_{xx}(p) = (u_\lambda)_{xx}(p), \quad u_{xy}(p) = (u_\lambda)_{xy}(p), \quad u_{yy}(p) = (u_\lambda)_{yy}(p)$.

Then, locally at p , the minimal surfaces Σ, Σ_λ intersect at $k \geq 3$ curves $\bar{\beta}_i$ meeting at p . By the maximum principle, $\Sigma \cap \Sigma_\lambda$ cannot contain a bounded curve, so the projection β_i of the curves $\bar{\beta}_i$ only intersect at p , and each one joints two different points in ∂D_λ .

Since u is an entire graph and u_λ equal $\pm\infty$ in ∂D_λ minus the vertices of D_λ , we conclude that each β_i joints two different vertices of D_λ . Thus at least two curves β_i finish at the same vertex of D_λ , which contradicts the General Maximum Principle. \square

Theorem 5.3 *Let $u : \mathbb{H}^2 \rightarrow \mathbb{R}$ be an entire vertical minimal graph. Denote by Σ the graph of u , and let $p \in \Sigma$.*

Then the absolute extrinsic curvature $|K_{ext}|$ of Σ at p is strictly smaller than the absolute extrinsic curvature $\kappa(p)$ of $\Sigma_{\lambda=\infty}$ at q , being q the point in $\Sigma_{\lambda=\infty}$ with the same unit normal and principal directions as Σ at p .

Moreover, this bound is best possible.

Proof. By Proposition 5.1, we know that $|K_{ext}|(p) < \kappa(p)$.

To finish Theorem 5.3, let us construct a sequence of entire minimal graphs converging to Σ_∞ .

Consider the Poincaré disk model of \mathbb{H}^2 . There exists [6] a (unique) minimal graph $u_n : \mathbb{H}^2 \rightarrow \mathbb{R}$ with boundary values n on $D_1 \cup D_3$, and $-n$ on $D_2 \cup D_4$ (cf. Figure 5), where

$$D_1 = \partial_\infty \mathbb{H}^2 \cap \{x_1 > |x_2|\}, \quad D_3 = \partial_\infty \mathbb{H}^2 \cap \{x_1 < -|x_2|\},$$

$$D_2 = \partial_\infty \mathbb{H}^2 \cap \{x_2 > |x_1|\}, \quad D_4 = \partial_\infty \mathbb{H}^2 \cap \{x_2 < -|x_1|\}.$$

Such minimal graph can be obtained by reflection from the minimal graph $v_n : \Omega \rightarrow \mathbb{R}$, where $\Omega = \{x_1 > |x_2|\}$, with boundary data n on D_1 and 0 on

$$\eta_1 = \{x_1 = x_2 > 0\} \quad \text{and} \quad \eta_1 = \{x_1 = -x_2 > 0\}.$$

Let Ω' be the ideal geodesic triangle bounded by η_1, η_2 and A_1 . And consider the minimal graph $v_\infty : \Omega' \rightarrow \mathbb{R}$ with boundary values 0 on $\eta_1 \cup \eta_2$ and $+\infty$ on A_1 .

By the General Maximum Principle,

$$\begin{aligned} 0 < v_n < v_{n+1}, & \quad \text{on } \Omega \\ v_n < v_\infty, & \quad \text{on } \Omega' \end{aligned}$$

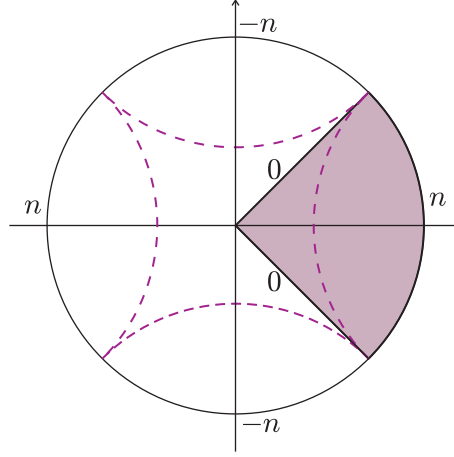


Figure 5:

for every n . Hence $\{v_n\}$ is a monotonically increasing sequence of minimal graphs on Ω , which is uniformly bounded on Ω' by v_∞ . Thus $\{v_n|_{\Omega'}\}_n$ converges to a minimal graph \tilde{v}_∞ on Ω' with the same boundary values as v_∞ . By uniqueness, we have $\tilde{v}_\infty = v_\infty$.

□

References

- [1] P. Collin and H. Rosenberg, *Construction of harmonic diffeomorphisms and minimal graphs*, Preprint (arXiv: math.DG/0701547).
- [2] R. Finn and R. Osserman, *On the Gauss curvature of non-parametric minimal surfaces*, J. Analysis Math., 12, 351-364 (1964).
- [3] E. Heinz, *Über die Lösungen der Minimalflächengleichung*, Nachr. Akad. Wiss. Göttingen, Math.-Phys. Kl., 51-56 (1952).
- [4] E. Hopf, *On an inequality for minimal surfaces $z = z(x, y)$* , J. Rat. Mech. Anal., 2, 519-522 (1953).
- [5] B. Nelli and H. Rosenberg, *Minimal surfaces in $\mathbb{H}^2 \times \mathbb{R}$* , Bulletin of the Brazilian Mathematical Society, 33 (2), 263-292 (2002).

- [6] L. Mazet, M.M. Rodríguez and H. Rosenberg, *The Dirichlet problem for the minimal surface equation - with possible infinite boundary data- over domains in a Riemannian surface*, preprint (arXiv:0806.0498).
- [7] R. Sa Earp, *Parabolic and hyperbolic screw motion surfaces in $\mathbb{H}^2 \times \mathbb{R}$* , J. Australian Math. Soc., 85, 113-143 (2008).
- [8] H.F. Scherk, *Bemerkungen über die kleinste Fläche innerhalb gegebener Grenzen*, J. R. Angew. Math., 13, 185-208 (1835).